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The Pan-European Cellular System

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27.1 Introduction

Following the standardization and launch of the Pan-European digital mobile cellular radio system known as GSM, it is of practical merit to provide a rudimentary introduction to the system's main features for the communications practitioner. Since GSM operating licenses have been allocated to 126 service providers in 75 countries, it is justifiable that the GSM system is often referred to as the Global System of Mobile communications.

The GSM specifications were released as 13 sets of recommendations [1], which are summarized in Table 27.1, covering various aspects of the system [3].

After a brief system overview in Section 27.2 and the introduction of physical and logical channels in Section 27.3 we embark upon describing aspects of mapping logical channels onto physical resources for speech and control channels in Sections 27.4 and 27.5, respectively. These details can be found in recommendations R.05.02 and R.05.03. These recommendations and all subsequently enumerated ones are to be found in [1]. Synchronization issues are considered in Section 27.6. Modulation (R.05.04), transmission via the standardized wideband GSM channel models (R.05.05), as well as adaptive radio link control (R.05.06 and R.05.08), discontinuous transmission (**DTX**) (R.06.31), and voice activity detection (**VAD**) (R.06.32) are highlighted in Sections 27.7–27.10, whereas a summary of the fundamental GSM features is offered in Section 27.11.

TABLE 27.1 GSM Recommendations [R.01.01]

R.00	<i>Preamble to the GSM recommendations</i>
R.01	<i>General structure</i> of the recommendations, description of a GSM network, associated recommendations, vocabulary, etc.
R.02	<i>Service aspects</i> : bearer-, tele- and supplementary services, use of services, types and features of mobile stations (MS), licensing and subscription, as well as transferred and international accounting, etc.
R.03	<i>Network aspects</i> , including network functions and architecture, call routing to the MS, technical performance, availability and reliability objectives, handover and location registration procedures, as well as discontinuous reception and cryptological algorithms, etc.
R.04	<i>Mobile/base station (BS) interface and protocols</i> , including specifications for layer 1 and 3 aspects of the open systems interconnection (OSI) seven-layer structure.
R.05	<i>Physical layer on the radio path</i> , incorporating issues of multiplexing and multiple access, channel coding and modulation, transmission and reception, power control, frequency allocation and synchronization aspects, etc.
R.06	<i>Speech coding specifications</i> , such as functional, computational and verification procedures for the speech codec and its associated voice activity detector (VAD) and other optional features.
R.07	<i>Terminal adaptors for MSs</i> , including circuit and packet mode as well as voiceband data services.
R.08	<i>Base station and mobile switching center (MSC) interface</i> , and transcoder functions.
R.09	<i>Network interworking</i> with the public switched telephone network (PSTN), integrated services digital network (ISDN) and, packet data networks.
R.10	<i>Service interworking, short message service</i> .
R.11	<i>Equipment specification and type approval specification</i> as regards to MSs, BSs, MSCs, home (HLR) and visited location register (VLR), as well as system simulator.
R.12	<i>Operation and maintenance</i> , including subscriber, routing tariff and traffic administration, as well as BS, MSC, HLR and VLR maintenance issues.

27.2 Overview

The system elements of a GSM public land mobile network (**PLMN**) are portrayed in Fig. 27.1, where their interconnections via the standardized interfaces A and Um are indicated as well. The mobile station (**MS**) communicates with the serving and adjacent base stations (**BS**) via the radio interface Um, whereas the BSs are connected to the mobile switching center (**MSC**) through the network interface A. As seen in Fig. 27.1, the MS includes a mobile termination (MT) and a terminal equipment (TE). The TE may be constituted, for example, by a telephone set and fax machine. The MT performs functions needed to support the physical channel between the MS and the base station, such as radio transmissions, radio channel management, channel coding/decoding, speech encoding/decoding, and so forth.

The BS is divided functionally into a number of base transceiver stations (BTS) and a base station controller (BSC). The BS is responsible for channel allocation (R.05.09), link quality and power budget control (R.05.06 and R.05.08), signalling and broadcast traffic control, frequency hopping (**FH**) (R.05.02), handover (**HO**) initiation (R.03.09 and R.05.08), etc. The MSC represents the gateway to other networks, such as the public switched telephone network (**PSTN**), integrated services digital network (**ISDN**) and packet data networks using the interworking functions standardized in recommendation R.09. The MSC's further functions include paging, MS location updating (R.03.12), HO control (R.03.09), etc. The MS's mobility management is assisted by the home location register (**HLR**) (R.03.12), storing part of the MS's location information and routing incoming calls to the visitor location register (**VLR**) (R.03.12) in charge of the area, where the paged MS roams. Location update is asked for by the MS, whenever it detects from the received and decoded broadcast control channel (**BCCH**) messages that it entered a new location area. The HLR contains, amongst a number of other parameters, the international mobile subscriber identity (**IMSI**), which is used for the authentication (R.03.20) of the subscriber by his authentication center (**AUC**). This enables the

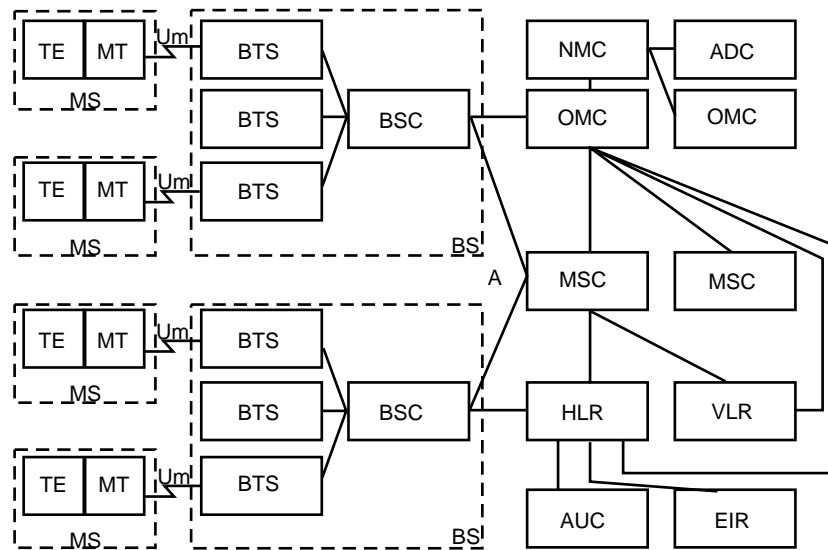


FIGURE 27.1: Simplified structure of GSM PLMN © ETT [4].

system to confirm that the subscriber is allowed to access it. Every subscriber belongs to a home network and the specific services that the subscriber is allowed to use are entered into his HLR. The equipment identity register (**EIR**) allows for stolen, fraudulent, or faulty mobile stations to be identified by the network operators. The VLR is the functional unit that attends to a MS operating outside the area of its HLR. The visiting MS is automatically registered at the nearest MSC, and the VLR is informed of the MSs arrival. A roaming number is then assigned to the MS, and this enables calls to be routed to it. The operations and maintenance center (**OMC**), network management center (**NMC**) and administration center (**ADC**) are the functional entities through which the system is monitored, controlled, maintained and managed (R.12).

The MS initiates a call by searching for a BS with a sufficiently high received signal level on the BCCH carrier; it will await and recognize a frequency correction burst and synchronize to it (R.05.08). Now the BS allocates a bidirectional signalling channel and also sets up a link with the MSC via the network. How the control frame structure assists in this process will be highlighted in Section 27.5. The MSC uses the IMSI received from the MS to interrogate its HLR and sends the data obtained to the serving VLR. After authentication (R.03.20) the MS provides the destination number, the BS allocates a traffic channel, and the MSC routes the call to its destination. If the MS moves to another cell, it is reassigned to another BS, and a handover occurs. If both BSs in the handover process are controlled by the same BSC, the handover takes place under the control of the BSC, otherwise it is performed by the MSC. In case of incoming calls the MS must be paged by the BSC. A paging signal is transmitted on a paging channel (**PCH**) monitored continuously by all MSs, and which covers the location area in which the MS roams. In response to the paging signal, the MS performs an access procedure identical to that employed when the MS initiates a call.

27.3 Logical and Physical Channels

The GSM logical traffic and control channels are standardized in recommendation R.05.02, whereas their mapping onto physical channels is the subject of recommendations R.05.02 and R.05.03. The GSM system's prime objective is to transmit the logical traffic channel's (**TCH**) speech or data information. Their transmission via the network requires a variety of logical control channels. The set of logical traffic and control channels defined in the GSM system is summarized in Table 27.2. There are two general forms of speech and data traffic channels: the full-rate traffic channels (**TCH/F**), which carry information at a gross rate of 22.8 kb/s, and the half-rate traffic channels (**TCH/H**), which communicate at a gross rate of 11.4 kb/s. A physical channel carries either a full-rate traffic channel, or two half-rate traffic channels. In the former, the traffic channel occupies one timeslot, whereas in the latter the two half-rate traffic channels are mapped onto the same timeslot, but in alternate frames.

TABLE 27.2 GSM Logical Channels © ETT [4]

Logical Channels					
Duplex BS ↔ MS Traffic Channels: TCH		Control Channels: CCH			
FEC-coded Speech	FEC-coded Data	Broadcast CCH BCCH BS → MS	Common CCH CCCH	Stand-alone Dedicated CCH SDCCH BS ↔ MS	Associated CCH ACCH BS ↔ MS
TCH/F 22.8 kb/s	TCH/F9.6 TCH/F4.8 TCH/F2.4 22.8 kb/s	Freq. Corr. Ch: FCCH	Paging Ch: PCH BS → MS	SDCCH/4	Fast ACCH: FACCH/F FACCH/H
TCH/H 11.4 kb/s	TCH/H4.8 TCH/H2.4 11.4 kb/s	Synchron. Ch: SCH	Random Access Ch: RACH MS → BS	SDCCH/8	Slow ACCH: SACCH/TF SACCH/TH SACCH/C4 SACCH/C8
		General Inf.	Access Grant Ch: AGCH BS → MS		

For a summary of the logical control channels carrying signalling or synchronisation data, see Table 27.2. There are four categories of logical control channels, known as the BCCH, the common control channel (**CCCH**), the stand-alone dedicated control channel (**SDCCH**), and the associated control channel (**ACCH**). The purpose and way of deployment of the logical traffic and control channels will be explained by highlighting how they are mapped onto physical channels in assisting high-integrity communications.

A physical channel in a time division multiple access (**TDMA**) system is defined as a timeslot with a timeslot number (TN) in a sequence of TDMA frames. The GSM system, however, deploys TDMA combined with frequency hopping (FH) and, hence, the physical channel is partitioned in both time and frequency. Frequency hopping (R.05.02) combined with interleaving is known to be very efficient in combatting channel fading, and it results in near-Gaussian performance even over hostile Rayleigh-fading channels. The principle of FH is that each TDMA burst is transmitted via a different RF channel (**RFCH**). If the present TDMA burst happened to be in a deep fade, then the next burst most probably will not be. Consequently, the physical channel is defined as a sequence of radio frequency channels and timeslots. Each carrier frequency supports eight physical channels mapped onto eight timeslots within a TDMA frame. A given physical channel always uses the same

TN in every TDMA frame. Therefore, a timeslot sequence is defined by a TN and a TDMA frame number FN sequence.

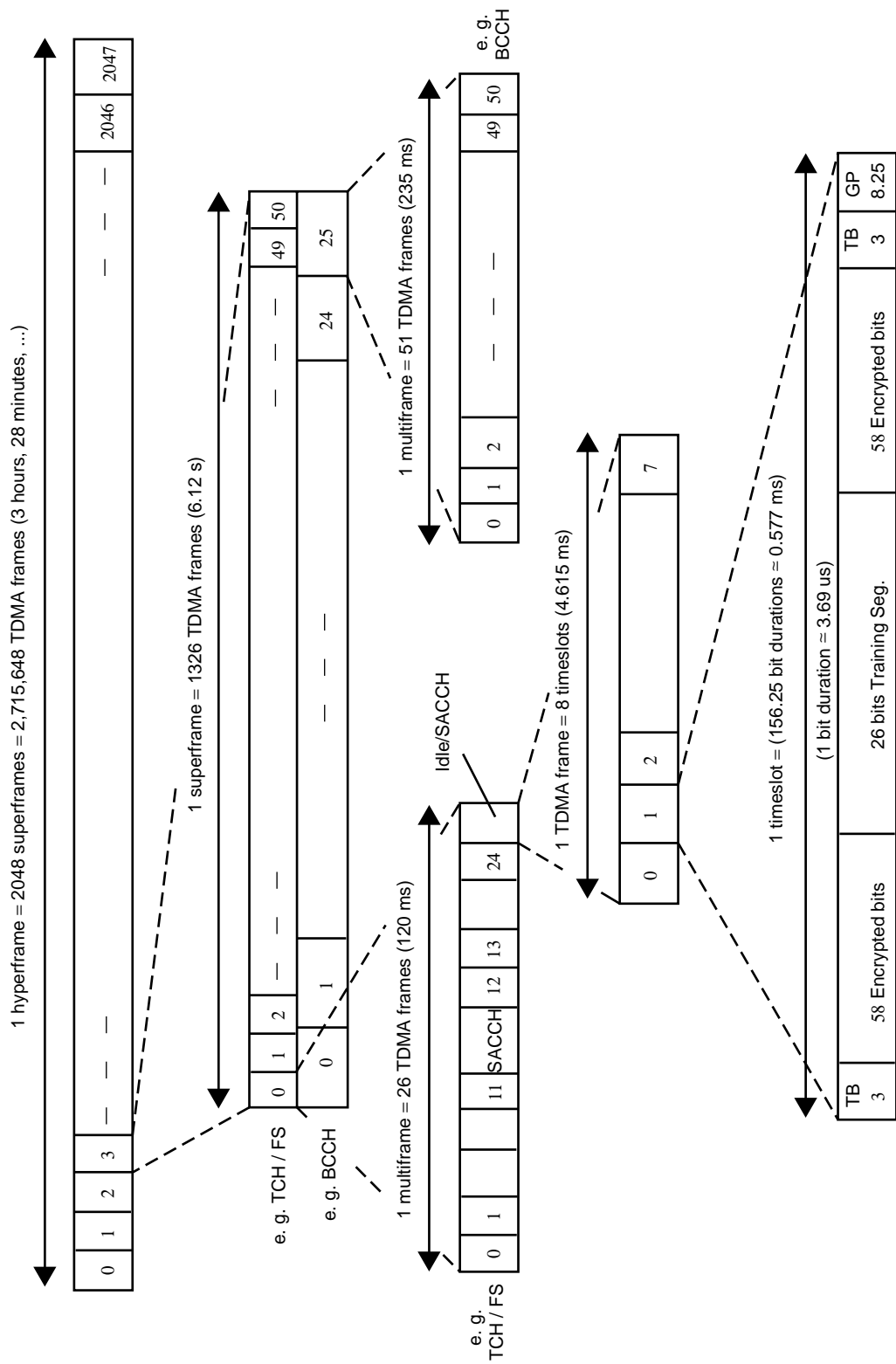
27.4 Speech and Data Transmission

The speech coding standard is recommendation R.06.10, whereas issues of mapping the logical speech traffic channel's information onto the physical channel constituted by a timeslot of a certain carrier are specified in recommendation R.05.02. Since the error correction coding represents part of this mapping process, recommendation R.05.03 is also relevant to these discussions. The example of the full-rate speech traffic channel (**TCH/FS**) is used here to highlight how this logical channel is mapped onto the physical channel constituted by a so-called normal burst (**NB**) of the TDMA frame structure. This mapping is explained by referring to Figs. 27.2 and 27.3. Then this example will be extended to other physical bursts such as the frequency correction (**FCB**), synchronization (**SB**), access (**AB**), and dummy burst (**DB**) carrying logical control channels, as well as to their TDMA frame structures, as seen in Figs. 27.2 and 27.6.

The regular pulse excited (**RPE**) speech encoder is fully characterized in the following references: [3, 5, 7]. Because of its complexity, its description is beyond the scope of this chapter. Suffice to say that, as it can be seen in Fig. 27.3, it delivers 260 b/20 ms at a bit rate of 13 kb/s, which are divided into three significance classes: class 1a (50 b), class 1b (132 b) and class 2 (78 b). The class-1a bits are encoded by a systematic (53, 50) cyclic error detection code by adding three parity bits. Then the bits are reordered and four zero tailing bits are added to periodically reset the memory of the subsequent half-rate, constraint length five convolutional codec (**CC**) CC(2, 1, 5), as portrayed in Fig. 27.3. Now the unprotected 78 class-2 bits are concatenated to yield a block of 456 b/20 ms, which implies an encoded bit rate of 22.8 kb/s. This frame is partitioned into eight 57-b subblocks that are block diagonally interleaved before undergoing intraburst interleaving. At this stage each 57-b subblock is combined with a similar subblock of the previous 456-b frame to construct a 116-b burst, where the flag bits *hl* and *hu* are included to classify whether the current burst is really a TCH/FS burst or it has been stolen by an urgent fast associated (**FACCH**) control channel message. Now the bits are encrypted and positioned in a NB, as depicted at the bottom of Fig. 27.2, where three tailing bits (**TB**) are added at both ends of the burst to reset the memory of the Viterbi channel equalizer (**VE**), which is responsible for removing both the channel-induced and the intentional controlled intersymbol interference [6].

The 8.25-b interval duration guard period (GP) at the bottom of Fig. 27.2 is provided to prevent burst overlapping due to propagation delay fluctuations. Finally, a 26-b equalizer training segment is included in the center of the normal traffic burst. This segment is constructed by a 16-b Viterbi channel equalizer training pattern surrounded by five quasiperiodically repeated bits on both sides. Since the MS has to be informed about which BS it communicates with, for neighboring BSs one of eight different training patterns is used, associated with the so-called BS color codes, which assist in identifying the BSs.

This 156.25-b duration TCH/FS NB constitutes the basic timeslot of the TDMA frame structure, which is input to the Gaussian minimum shift keying (**GMSK**) modulator to be highlighted in Section 27.7, at a bit rate of approximately 271 kb/s. Since the bit interval is $1/(271 \text{ kb/s}) = 3.69 \mu\text{s}$, the timeslot duration is $156.25 \cdot 3.69 \approx 0.577 \text{ ms}$. Eight such normal bursts of eight appropriately staggered TDMA users are multiplexed onto one (**RF**) carrier giving, a TDMA frame of $8 \cdot 0.577 \approx 4.615 \text{ ms}$ duration, as shown in Fig. 27.2. The physical channel as characterized earlier provides a physical timeslot with a throughput of $114 \text{ b}/4.615 \text{ ms} = 24.7 \text{ kb/s}$, which is sufficiently high to transmit the 22.8 kb/s TCH/FS information. It even has a reserved capacity of $24.7 - 22.8 =$



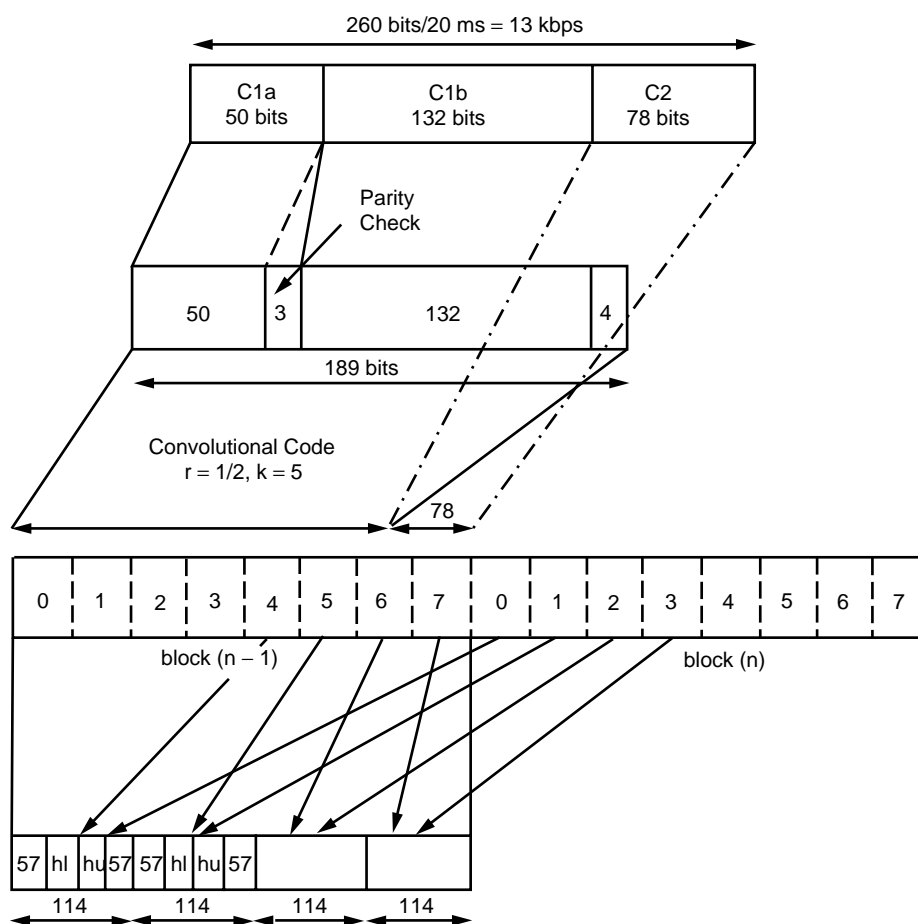


FIGURE 27.3: Mapping the TCH/FS logical channel onto a physical channel, ©ETT [4].

1.9 kb/s, which can be exploited to transmit slow control information associated with this specific traffic channel, i.e., to construct a so-called slow associated control channel (**SACCH**), constituted by the SACCH TDMA frames, interspersed with traffic frames at multiframe level of the hierarchy, as seen in Fig. 27.2.

Mapping logical data traffic channels onto a physical channel is essentially carried out by the channel codecs [8], as specified in recommendation R.05.03. The full- and half-rate data traffic channels standardized in the GSM system are: **TCH/F9.6**, **TCH/F4.8**, **TCH/F2.4**, as well as **TCH/H4.8**, **TCH/H2.4**, as was shown earlier in Table 27.2. Note that the numbers in these acronyms represent the data transmission rate in kilobits per second. Without considering the details of these mapping processes we now focus our attention on control signal transmission issues.

27.5 Transmission of Control Signals

The exact derivation, forward error correcting (**FEC**) coding and mapping of logical control channel information is beyond the scope of this chapter, and the interested reader is referred to ETSI, 1988

(R.05.02 and R.05.03) and Hanzo and Stefanov, 1992, for a detailed discussion. As an example, the mapping of the 184-b SACCH, FACCH, BCCH, SDCCH, PCH, and access grant control channel (**AGCH**) messages onto a 456-b block, i.e., onto four 114-b bursts is demonstrated in Fig. 27.4. A double-layer concatenated FIRE-code/convolutional code scheme generates 456 bits, using an overall coding rate of $R = 184/456$, which gives a stronger protection for control channels than the error protection of traffic channels.

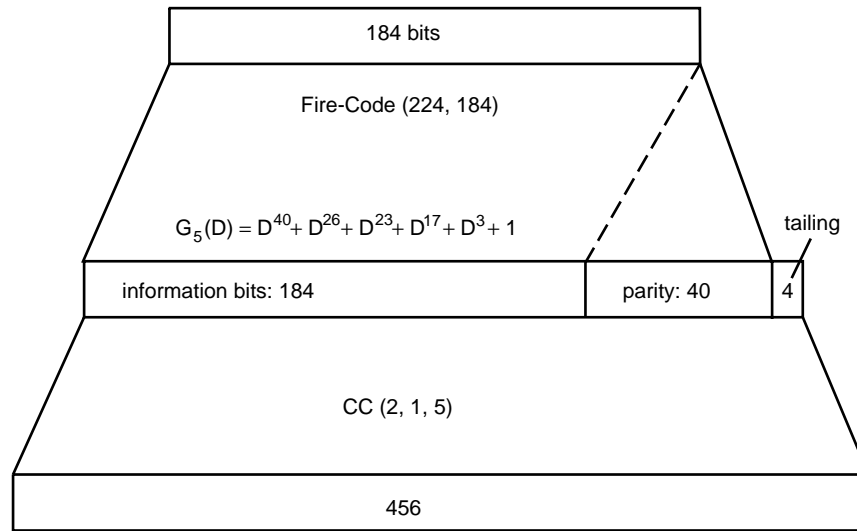


FIGURE 27.4: FEC in SACCH, FACCH, BCCH, SDCCH, PCH and AGCH, ©ETT [4].

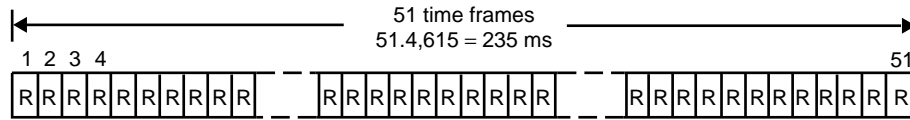
Returning to Fig. 27.2 we will now show how the SACCH is accommodated by the TDMA frame structure. The TCH/FS TDMA frames of the eight users are multiplexed into multiframes of 24 TDMA frames, but the 13th frame will carry a SACCH message, rather than the 13th TCH/FS frame, whereas the 26th frame will be an idle or dummy frame, as seen at the left-hand side of Fig. 27.2 at the multiframe level of the traffic channel hierarchy. The general control channel frame structure shown at the right of Fig. 27.2 is discussed later. This way 24-TCH/FS frames are sent in a 26-frame multiframe during $26 \cdot 4.615 = 120$ ms. This reduces the traffic throughput to $(24/26) \cdot 24.7 = 22.8$ kb/s required by TCH/FS, allocates $(1/26) \cdot 24.7 = 950$ b/s to the SACCH and wastes 950 b/s in the idle frame. Observe that the SACCH frame has eight timeslots to transmit the eight 950-b/s SACCHs of the eight users on the same carrier. The 950-b/s idle capacity will be used in case of half-rate channels, where 16 users will be multiplexed onto alternate frames of the TDMA structure to increase system capacity. Then 16, 11.4-kb/s encoded half-rate speech TCHs will be transmitted in a 120-ms multiframe, where also 16 SACCHs are available.

The FACCH messages are transmitted via the physical channels provided by bits stolen from their own host traffic channels. The construction of the FACCH bursts from 184 control bits is identical to that of the SACCH, as also shown in Fig. 27.4 but its 456-b frame is mapped onto eight consecutive 114-b TDMA traffic bursts, exactly as specified for TCH/FS. This is carried out by stealing the even bits of the first four and the odd bits of the last four bursts, which is signalled by setting $hu = 1, hl = 0$ and $hu = 0, hl = 1$ in the first and last bursts, respectively. The unprotected FACCH information

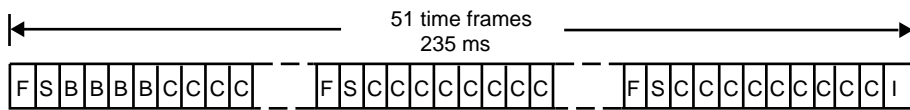
rate is $184 \text{ b}/20 \text{ ms} = 9.2 \text{ kb/s}$, which is transmitted after concatenated error protection at a rate of 22.8 kb/s . The repetition delay is 20 ms , and the interleaving delay is $8 \cdot 4.615 = 37 \text{ ms}$, resulting in a total of 57-ms delay.

In Fig. 27.2 at the next hierarchical level, 51-TCH/FS multiframes are multiplexed into one superframe lasting $51 \cdot 120 \text{ ms} = 6.12 \text{ s}$, which contains $26 \cdot 51 = 1326\text{-TDMA}$ frames. In the case of 1326-TDMA frames, however, the frame number would be limited to $0 \leq FN \leq 1326$ and the encryption rule relying on such a limited range of FN values would not be sufficiently secure. Then 2048 superframes were amalgamated to form a hyperframe of $1326 \cdot 2048 = 2,715,648\text{-TDMA}$ frames lasting $2048 \cdot 6.12 \text{ s} \approx 3 \text{ h } 28 \text{ min}$, allowing a sufficiently high FN value to be used in the encryption algorithm. The uplink and downlink traffic-frame structures are identical with a shift of three timeslots between them, which relieves the MS from having to transmit and receive simultaneously, preventing high-level transmitted power leakage back to the sensitive receiver. The received power of adjacent BSs can be monitored during unallocated timeslots.

In contrast to duplex traffic and associated control channels, the simplex BCCH and CCCH logical channels of all MSs roaming in a specific cell share the physical channel provided by timeslot zero of the so-called BCCH carriers available in the cell. Furthermore, as demonstrated by the right-hand side section of Fig. 27.2, 51 BCCH and CCCH TDMA frames are mapped onto a $51 \cdot 4.615 = 235\text{-ms}$ duration multiframe, rather than on a 26-frame, 120-ms duration multiframe. In order to compensate for the extended multiframe length of 235 ms , 26 multiframes constitute a 1326-frame superframe of 6.12-s duration. Note in Fig. 27.5, that the allocation of the uplink and downlink frames is different, since these control channels exist only in one direction.



(a) Uplink Direction



(a) Downlink Direction

- R: Random Access Channel
- F : Frequency Correction Channel
- S: Synchronisation Channel
- B: Broadcast Control Channel
- C: Access Grant/Paging Channel
- I : Idle Frame

FIGURE 27.5: The control multiframe, ©ETT [4].

Specifically, the random access channel (**RACH**) is only used by the MSs in the uplink direction if they request, for example, a bidirectional SDCCH to be mapped onto an RF channel to register with the network and set up a call. The uplink RACH has a low capacity, carrying messages of 8-b/235-ms multiframe, which is equivalent to an unprotected control information rate of 34 b/s. These messages are concatenated FEC coded to a rate of 36 b/235 ms = 153 b/s. They are not transmitted by the NB derived for TCH/FS, SACCH, or FACCH logical channels, but by the AB, depicted in Fig. 27.6 in comparison to a NB and other types of bursts to be described later. The FEC coded, encrypted 36-b AB messages of Fig. 27.6 contain among other parameters, the encoded 6-b BS identifier code (**BSIC**) constituted by the 3-b PLMN color code and 3-b BS color code for unique BS identification. These 36 b are positioned after the 41-b synchronization sequence, which has a high wordlength in order to ensure reliable access burst recognition and a low probability of being emulated by interfering stray data. These messages have no interleaving delay, while they are transmitted with a repetition delay of one control multiframe length, i.e., 235 ms.

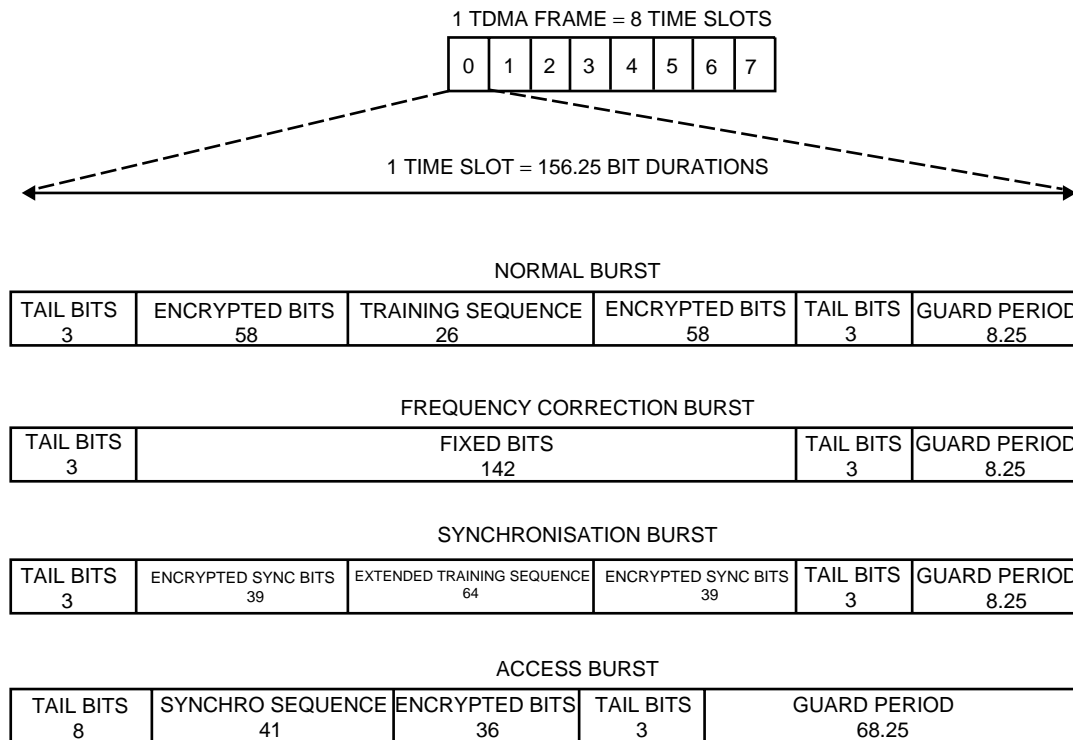


FIGURE 27.6: GSM burst structures, © ETT [4].

Adaptive time frame alignment is a technique designed to equalize propagation delay differences between MSs at different distances. The GSM system is designed to allow for cell sizes up to 35 km radius. The time a radio signal takes to travel the 70 km from the base station to the mobile station and back again is 233.3 μ s. As signals from all the mobiles in the cell must reach the base station without overlapping each other, a long guard period of 68.25 b (252 μ s) is provided in the access

burst, which exceeds the maximum possible propagation delay of $233.3 \mu\text{s}$. This long guard period in the access burst is needed when the mobile station attempts its first access to the base station or after a handover has occurred. When the base station detects a 41-b random access synchronization sequence with a long guard period, it measures the received signal delay relative to the expected signal from a mobile station of zero range. This delay, called the timing advance, is signalled using a 6-b number to the mobile station, which advances its timebase over the range of 0–63 b, i.e., in units of $3.69 \mu\text{s}$. By this process the TDMA bursts arrive at the BS in their correct timeslots and do not overlap with adjacent ones. This process allows the guard period in all other bursts to be reduced to $8.25 \cdot 3.69 \mu\text{s} \approx 30.46 \mu\text{s}$ (8.25 b) only. During normal operation, the BS continuously monitors the signal delay from the MS and, if necessary, it will instruct the MS to update its time advance parameter. In very large traffic cells there is an option to actively utilize every second timeslot only to cope with higher propagation delays, which is spectrally inefficient, but in these large, low-traffic rural cells it is admissible.

As demonstrated by Fig. 27.2, the downlink multiframe transmitted by the BS is shared amongst a number of BCCH and CCCH logical channels. In particular, the last frame is an idle frame (I), whereas the remaining 50 frames are divided in five blocks of ten frames, where each block starts with a frequency correction channel (FCCH) followed by a synchronization channel (SCH). In the first block of ten frames the FCCH and SCH frames are followed by four BCCH frames and by either four AGCH or four PCH. In the remaining four blocks of ten frames, the last eight frames are devoted to either PCHs or AGCHs, which are mutually exclusive for a specific MS being either paged or granted a control channel.

The FCCH, SCH, and RACH require special transmission bursts, tailored to their missions, as depicted in Fig. 27.6. The FCCH uses frequency correction bursts (FCB) hosting a specific 142-b pattern. In partial response GMSK it is possible to design a modulating data sequence, which results in a near-sinusoidal modulated signal imitating an unmodulated carrier exhibiting a fixed frequency offset from the RF carrier utilized. The synchronization channel transmits SB hosting a $16 \cdot 4 = 64$ -b extended sequence exhibiting a high-correlation peak in order to allow frame alignment with a quarter-bit accuracy. Furthermore, the SB contains $2 \cdot 39 = 78$ encrypted FEC-coded synchronization bits, hosting the BS and PLMN color codes, each representing one of eight legitimate identifiers. Lastly, the AB contain an extended 41-b synchronization sequence, and they are invoked to facilitate initial access to the system. Their long guard space of 68.25-b duration prevents frame overlap, before the MS's distance, i.e., the propagation delay becomes known to the BS and could be compensated for by adjusting the MS's timing advance.

27.6 Synchronization Issues

Although some synchronization issues are standardized in recommendations R.05.02 and R.05.03, the GSM recommendations do not specify the exact BS-MS synchronization algorithms to be used, these are left to the equipment manufacturers. A unique set of timebase counters, however, is defined in order to ensure perfect BS-MS synchronism. The BS sends FCB and SB on specific timeslots of the BCCH carrier to the MS to ensure that the MS's frequency standard is perfectly aligned with that of the BS, as well as to inform the MS about the required initial state of its internal counters. The MS transmits its uniquely numbered traffic and control bursts staggered by three timeslots with respect to those of the BS to prevent simultaneous MS transmission and reception, and also takes into account the required timing advance (TA) to cater for different BS-MS round-trip delays.

The timebase counters used to uniquely describe the internal timing states of BSs and MSs are the quarter-bit number ($QN = 0\text{--}624$) counting the quarter-bit intervals in bursts, bit number

($BN = 0-156$), timeslot number ($TN = 0-7$) and TDMA Frame Number ($FN = 0-26 \cdot 51 \cdot 2048$), given in the order of increasing interval duration. The MS sets up its timebase counters after receiving a SB by determining QN from the 64-b extended training sequence in the center of the SB, setting $TN = 0$ and decoding the 78-encrypted, protected bits carrying the 25-SCH control bits.

The SCH carries frame synchronization information as well as BS identification information to the MS, as seen in Fig. 27.7, and it is provided solely to support the operation of the radio subsystem. The first 6 b of the 25-b segment consist of three PLMN color code bits and three

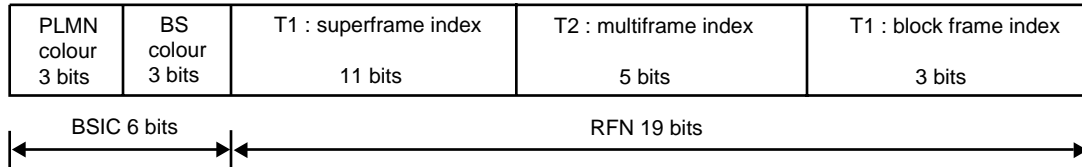


FIGURE 27.7: Synchronization channel (SCH) message format, ©ETT [4].

BS color code bits supplying a unique BS identifier code (BSIC) to inform the MS which BS it is communicating with. The second 19-bit segment is the so-called reduced TDMA frame number **RFN** derived from the full TDMA frame number FN , constrained to the range of $[0-(26 \cdot 51 \cdot 2048) - 1] = (0-2,715,647)$ in terms of three subsegments $T1$, $T2$, and $T3$. These subsegments are computed as follows: $T1(11 \text{ b}) = [FN \text{ div } (26 \cdot 51)]$, $T2(5 \text{ b}) = (FN \text{ mod } 26)$ and $T3'(3 \text{ b}) = [(T3 - 1) \text{ div } 10]$, where $T3 = (FN \text{ mod } 5)$, whereas div and mod represent the integer division and modulo operations, respectively. Explicitly, in Fig. 27.7 $T1$ determines the superframe index in a hyperframe, $T2$ the multiframe index in a superframe, $T3$ the frame index in a multiframe, whereas $T3'$ is the so-called signalling block index [1–5] of a frame in a specific 51-frame control multiframe, and their roles are best understood by referring to Fig. 27.2. Once the MS has received the SB, it readily computes the FN required in various control algorithms, such as encryption, handover, etc., as

$$FN = 51 [(T3 - T2) \text{ mod } 26] + T3 + 51 \cdot 26 \cdot T1, \quad \text{where } T3 = 10 \cdot T3' + 1$$

27.7 Gaussian Minimum Shift Keying Modulation

The GSM system uses constant envelope partial response GMSK modulation [6] specified in recommendation R.05.04. Constant envelope, continuous-phase modulation schemes are robust against signal fading as well as interference and have good spectral efficiency. The slower and smoother are the phase changes, the better is the spectral efficiency, since the signal is allowed to change less abruptly, requiring lower frequency components. The effect of an input bit, however, is spread over several bit periods, leading to a so-called partial response system, which requires a channel equalizer in order to remove this controlled, intentional intersymbol interference (ISI) even in the absence of uncontrolled channel dispersion.

The widely employed partial response GMSK scheme is derived from the full response minimum shift keying (MSK) scheme. In MSK the phase changes between adjacent bit periods are piecewise linear, which results in discontinuous-phase derivative, i.e., instantaneous frequency at the signalling instants, and hence widens the spectrum. Smoothing these phase changes, however, by a filter having

a Gaussian impulse response [6], which is known to have the lowest possible bandwidth, this problem is circumvented using the schematic of Fig. 27.8, where the GMSK signal is generated by modulating and adding two quadrature carriers. The key parameter of GMSK in controlling both bandwidth and interference resistance is the 3-dB down filter-bandwidth \times bit interval product ($B \cdot T$), referred to as normalized bandwidth. It was found that as the $B \cdot T$ product is increased from 0.2 to 0.5, the interference resistance is improved by approximately 2 dB at the cost of increased bandwidth occupancy, and best compromise was achieved for $B \cdot T = 0.3$. This corresponds to spreading the effect of 1 b over approximately 3-b intervals. The spectral efficiency gain due to higher interference tolerance and, hence, more dense frequency reuse was found to be more significant than the spectral loss caused by wider GMSK spectral lobes.

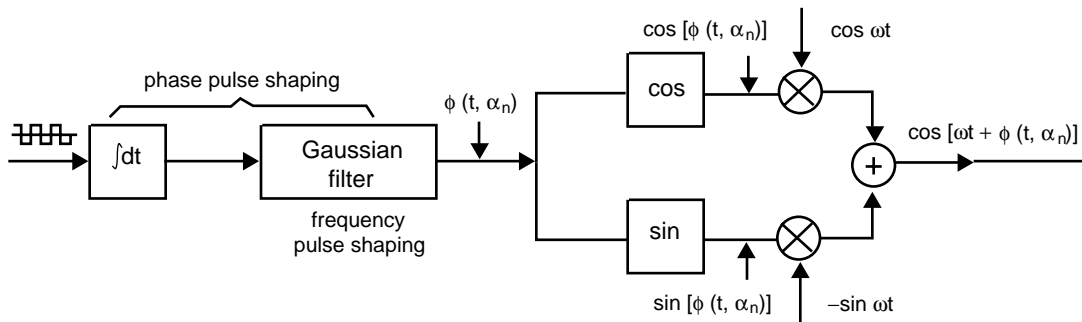


FIGURE 27.8: GMSK modulator schematic diagram, ©ETT [4].

The channel separation at the TDMA burst rate of 271 kb/s is 200 kHz, and the modulated spectrum must be 40 dB down at both adjacent carrier frequencies. When TDMA bursts are transmitted in an on-off keyed mode, further spectral spillage arises, which is mitigated by a smooth power ramp up and down envelope at the leading and trailing edges of the transmission bursts, attenuating the signal by 70 dB during a 28- and 18- μ s interval, respectively.

27.8 Wideband Channel Models

The set of 6-tap GSM impulse responses [2] specified in recommendation R.05.05 is depicted in Fig. 27.9, where the individual propagation paths are independent Rayleigh fading paths, weighted by the appropriate coefficients h_i corresponding to their relative powers portrayed in the figure. In simple terms the wideband channel's impulse response is measured by transmitting an impulse and detecting the received echoes at the channel's output in every D -spaced so-called delay bin. In some bins no delayed and attenuated multipath component is received, whereas in others significant energy is detected, depending on the typical reflecting objects and their distance from the receiver. The path delay can be easily related to the distance of the reflecting objects, since radio waves are travelling at the speed of light. For example, at a speed of 300,000 km/s, a reflecting object situated at a distance of 0.15 km yields a multipath component at a round-trip delay of 1 μ s.

The typical urban (TU) impulse response spreads over a delay interval of 5 μ s, which is almost two 3.69- μ s bit-intervals duration and, therefore, results in serious ISI. In simple terms, it can be treated as a two-path model, where the reflected path has a length of 0.75 km, corresponding to a reflector

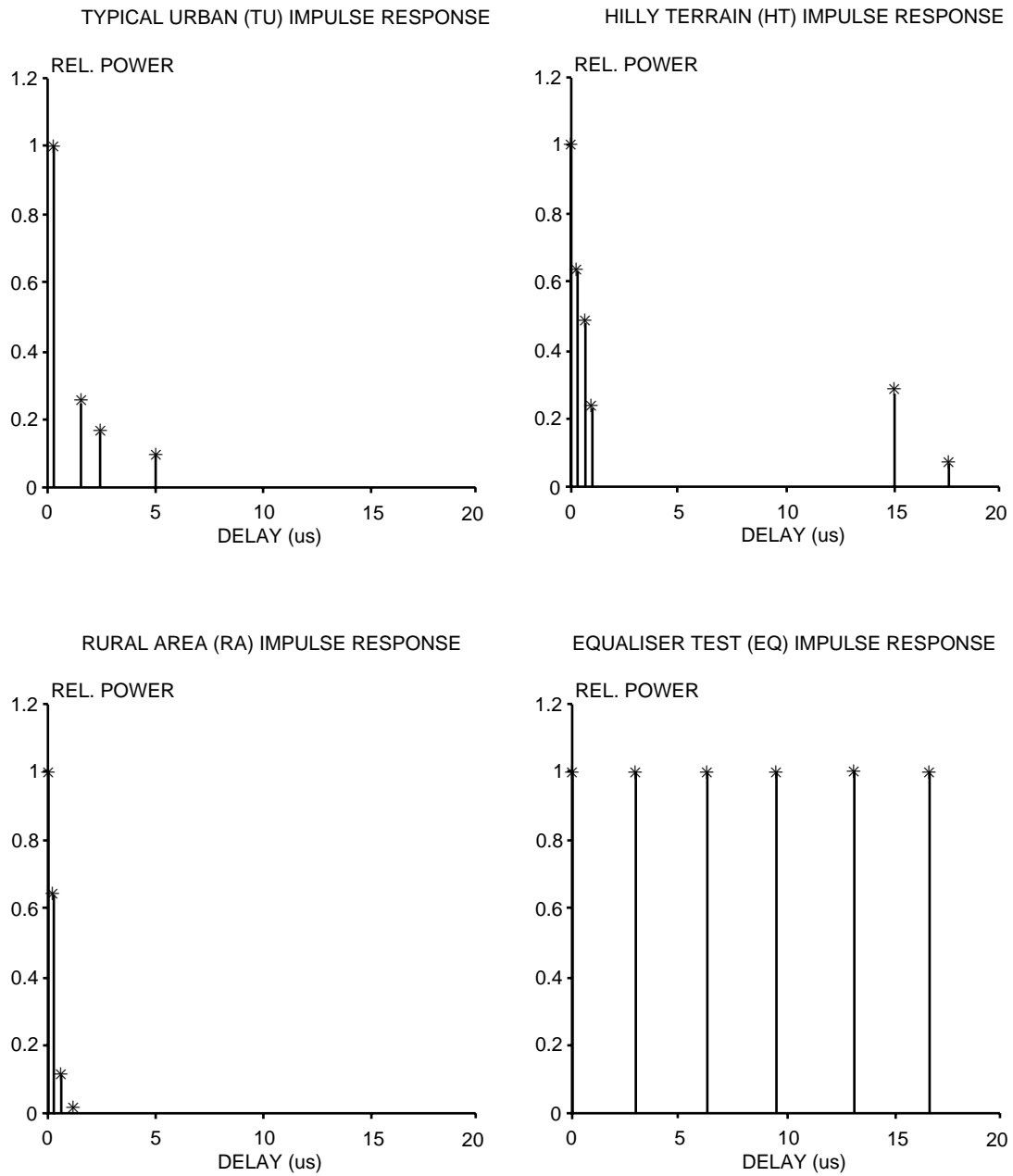


FIGURE 27.9: Typical GSM channel impulse responses, © ETT [4].

located at a distance of about 375 m. The hilly terrain (HT) model has a sharply decaying short-delay section due to local reflections and a long-delay path around $15\ \mu\text{s}$ due to distant reflections. Therefore, in practical terms it can be considered a two- or three-path model having reflections from a distance of about 2 km. The rural area (RA) response seems the least hostile amongst all standardized responses, decaying rapidly inside 1-b interval and, therefore, is expected to be easily combated by the channel equalizer. Although the type of the equalizer is not standardized, partial response systems typically use VEs. Since the RA channel effectively behaves as a single-path nondispersive channel, it would not require an equalizer. The fourth standardized impulse response is artificially contrived in order to test the equalizer's performance and is constituted by six equidistant unit-amplitude impulses representing six equal-powered independent Rayleigh-fading paths with a delay spread over $16\ \mu\text{s}$. With these impulse responses in mind, the required channel is simulated by summing the appropriately delayed and weighted received signal components. In all but one case the individual components are assumed to have Rayleigh amplitude distribution, whereas in the RA model the main tap at zero delay is supposed to have a Rician distribution with the presence of a dominant line-of-sight path.

27.9 Adaptive Link Control

The adaptive link control algorithm portrayed in Fig. 27.10 and specified in recommendation R.05.08 allows for the MS to favor that specific traffic cell which provides the highest probability of reliable communications associated with the lowest possible path loss. It also decreases interference with other cochannel users and, through dense frequency reuse, improves spectral efficiency, whilst maintaining an adequate communications quality, and facilitates a reduction in power consumption, which is particularly important in hand-held MSs. The handover process maintains a call in progress as the MS moves between cells, or when there is an unacceptable transmission quality degradation caused by interference, in which case an intracell handover to another carrier in the same cell is performed. A radio-link failure occurs when a call with an unacceptable voice or data quality cannot be improved either by RF power control or by handover. The reasons for the link failure may be loss of radio coverage or very high-interference levels. The link control procedures rely on measurements of the received RF signal strength (RXLEV), the received signal quality (RXQUAL), and the absolute distance between base and mobile stations (DISTANCE).

RXLEV is evaluated by measuring the received level of the BCCH carrier which is continuously transmitted by the BS on all time slots of the B frames in Fig. 27.5 and without variations of the RF level. A MS measures the received signal level from the serving cell and from the BSs in all adjacent cells by tuning and listening to their BCCH carriers. The root mean squared level of the received signal is measured over a dynamic range from -103 to -41 dBm for intervals of one SACCH multiframe (480 ms). The received signal level is averaged over at least 32 SACCH frames (≈ 15 s) and mapped to give RXLEV values between 0 and 63 to cover the range from -103 to -41 dBm in steps of 1 dB. The RXLEV parameters are then coded into 6-b words for transmission to the serving BS via the SACCH.

RXQUAL is estimated by measuring the bit error ratio (BER) before channel decoding, using the Viterbi channel equalizer's metrics [6] and/or those of the Viterbi convolutional decoder [8]. Eight values of RXQUAL span the logarithmically scaled BER range of 0.2–12.8% before channel decoding.

The absolute DISTANCE between base and mobile stations is measured using the timing advance parameter. The timing advance is coded as a 6-b number corresponding to a propagation delay from 0 to $63 \cdot 3.69\ \mu\text{s} = 232.6\ \mu\text{s}$, characteristic of a cell radius of 35 km.

While roaming, the MS needs to identify which potential target BS it is measuring, and the BCCH carrier frequency may not be sufficient for this purpose, since in small cluster sizes the same BCCH

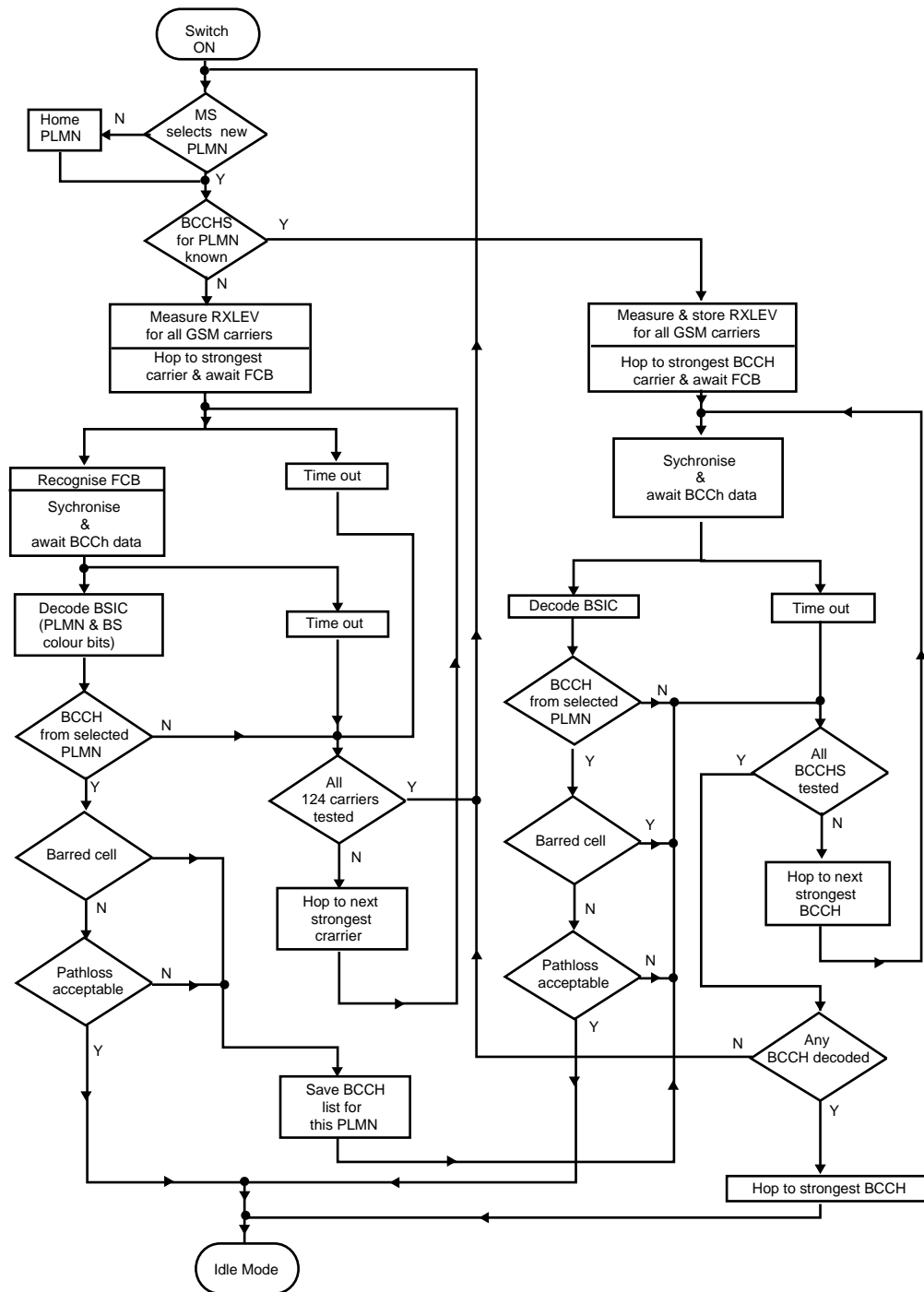


FIGURE 27.10: Initial cell selection by the MS, © ETT [4].

frequency may be used in more than one surrounding cell. To avoid ambiguity a 6-b BSIC is transmitted on each BCCH carrier in the SB of Fig. 27.6. Two other parameters transmitted in the BCCH data provide additional information about the BS. The binary flag called **PLMN PERMITTED** indicates whether the measured BCCH carrier belongs to a PLMN that the MS is permitted to access. The second Boolean flag, **CELL BAR ACCESS**, indicates whether the cell is barred for access by the MS, although it belongs to a permitted PLMN. A MS in idle mode, i.e., after it has just been switched on or after it has lost contact with the network, searches all 125 RF channels and takes readings of RXLEV on each of them. Then it tunes to the carrier with the highest RXLEV and searches for FCB in order to determine whether or not the carrier is a BCCH carrier. If it is not, then the MS tunes to the next highest carrier, and so on, until it finds a BCCH carrier, synchronizes to it and decodes the parameters BSIC, PLMN_PERMITTED and CELL_BAR_ACCESS in order to decide whether to continue the search. The MS may store the BCCH carrier frequencies used in the network accessed, in which case the search time would be reduced. Again, the process described is summarized in the flowchart of Fig. 27.10.

The adaptive power control is based on RXLEV measurements. In every SACCH multiframe the BS compares the RXLEV readings reported by the MS or obtained by the base station with a set of thresholds. The exact strategy for RF power control is determined by the network operator with the aim of providing an adequate quality of service for speech and data transmissions while keeping interferences low. Clearly, adequate quality must be achieved at the lowest possible transmitted power to keep cochannel interferences low, which implies contradictory requirements in terms of transmitted power. The criteria for reporting radio link failure are based on the measurements of RXLEV and RXQUAL performed by both the mobile and base stations, and the procedures for handling link failures result in the re-establishment or the release of the call, depending on the network operator's strategy.

The handover process involves the most complex set of procedures in the radio-link control. Handover decisions are based on results of measurements performed both by the base and mobile stations. The base station measures RXLEV, RXQUAL, DISTANCE, and also the interference level in unallocated time slots, whereas the MS measures and reports to the BS the values of RXLEV and RXQUAL for the serving cell and RXLEV for the adjacent cells. When the MS moves away from the BS, the RXLEV and RXQUAL parameters for the serving station become lower, whereas RXLEV for one of the adjacent cells increases.

27.10 Discontinuous Transmission

Discontinuous transmission (DTX) issues are standardized in recommendation R.06.31, whereas the associated problems of voice activity detection VAD are specified by R.06.32. Assuming an average speech activity of 50% and a high number of interferers combined with frequency hopping to randomize the interference load, significant spectral efficiency gains can be achieved when deploying discontinuous transmissions due to decreasing interferences, while reducing power dissipation as well. Because of the reduction in power consumption, full DTX operation is mandatory for MSs, but in BSs, only receiver DTX functions are compulsory.

The fundamental problem in voice activity detection is how to differentiate between speech and noise, while keeping false noise triggering and speech spurt clipping as low as possible. In vehicle-mounted MSs the severity of the speech/noise recognition problem is aggravated by the excessive vehicle background noise. This problem is resolved by deploying a combination of threshold comparisons and spectral domain techniques [1, 3]. Another important associated problem is the intro-

duction of noiseless inactive segments, which is mitigated by comfort noise insertion (CNI) in these segments at the receiver.

27.11 Summary

Following the standardization and launch of the GSM system its salient features were summarized in this brief review. Time division multiple access (TDMA) with eight users per carrier is used at a multiuser rate of 271 kb/s, demanding a channel equalizer to combat dispersion in large cell environments. The error protected chip rate of the full-rate traffic channels is 22.8 kb/s, whereas in half-rate channels it is 11.4 kb/s. Apart from the full- and half-rate speech traffic channels, there are 5 different rate data traffic channels and 14 various control and signalling channels to support the system's operation. A moderately complex, 13 kb/s regular pulse excited speech codec with long term predictor (LTP) is used, combined with an embedded three-class error correction codec and multilayer interleaving to provide sensitivity-matched unequal error protection for the speech bits. An overall speech delay of 57.5 ms is maintained. Slow frequency hopping at 217 hops/s yields substantial performance gains for slowly moving pedestrians.

TABLE 27.3 Summary of GSM Features

System feature	Specification
Up-link bandwidth, MHz	890–915 = 25
Down-link bandwidth, MHz	935–960 = 25
Total GSM bandwidth, MHz	50
Carrier spacing, KHz	200
No. of RF carriers	125
Multiple access	TDMA
No. of users/carrier	8
Total No. of channels	1000
TDMA burst rate, kb/s	271
Modulation	GMSK with BT = 0.3
Bandwidth efficiency, b/s/Hz	1.35
Channel equalizer	yes
Speech coding rate, kb/s	13
FEC coded speech rate, kb/s	22.8
FEC coding	Embedded block/ convolutional
Frequency hopping, hop/s	217
DTX and VAD	yes
Maximum cell radius, km	35

Constant envelope partial response GMSK with a channel spacing of 200 kHz is deployed to support 125 duplex channels in the 890–915-MHz up-link and 935–960-MHz down-link bands, respectively. At a transmission rate of 271 kb/s a spectral efficiency of 1.35-bit/s/Hz is achieved. The controlled GMSK-induced and uncontrolled channel-induced intersymbol interferences are removed by the channel equalizer. The set of standardized wideband GSM channels was introduced in order to provide bench markers for performance comparisons. Efficient power budgeting and minimum

cochannel interferences are ensured by the combination of adaptive power and handover control based on weighted averaging of up to eight up-link and down-link system parameters. Discontinuous transmissions assisted by reliable spectral-domain voice activity detection and comfort-noise insertion further reduce interferences and power consumption. Because of ciphering, no unprotected information is sent via the radio link. As a result, spectrally efficient, high-quality mobile communications with a variety of services and international roaming is possible in cells of up to 35 km radius for signal-to-noise and interference ratios in excess of 10–12 dBs. The key system features are summarized in Table 27.3.

Defining Terms

A3: Authentication algorithm

A5: Cyphering algorithm

A8: Confidential algorithm to compute the cyphering key

AB: Access burst

ACCH: Associated control channel

ADC: Administration center

AGCH: Access grant control channel

AUC: Authentication center

AWGN: Additive Gaussian noise

BCCH: Broadcast control channel

BER: Bit error ratio

BFI: Bad frame indicator flag

BN: Bit number

BS: Base station

BS-PBGT: BS powerbudget: to be evaluated for power budget motivated handovers

BSIC: Base station identifier code

CC: Convolutional codec

CCCH: Common control channel

CELL.BAR.ACCESS: Boolean flag to indicate, whether the MS is permitted to access the specific traffic cell

CNC: Comfort noise computation

CNI: Comfort noise insertion

CNU: Comfort noise update state in the DTX handler

DB: Dummy burst

DL: Down link

DSI: Digital speech interpolation to improve link efficiency

DTX: Discontinuous transmission for power consumption and interference reduction

EIR: Equipment identity register

EOS: End of speech flag in the DTX handler

FACCH: Fast associated control channel

FCB: Frequency correction burst

FCCH: Frequency correction channel
FEC: Forward error correction
FH: Frequency hopping
 FN : TDMA frame number
GMSK: Gaussian minimum shift keying
GP: Guard space
HGO: Handover in the VAD
HLR: Home location register
HO: Handover
HOCT: Handover counter in the VAD
HO_MARGIN: Handover margin to facilitate hysteresis
HSN: Hopping sequence number: frequency hopping algorithm's input variable
IMSI: International mobile subscriber identity
ISDN: Integrated services digital network
LAI: Location area identifier
LAR: Logarithmic area ratio
LTP: Long term predictor
MA: Mobile allocation: set of legitimate RF channels, input variable in the frequency hopping algorithm
MAI: Mobile allocation index: output variable of the FH algorithm
MAIO: Mobile allocation index offset: initial RF channel offset, input variable of the FH algorithm
MS: Mobile station
MSC: Mobile switching center
MSRN: Mobile station roaming number
MS_TXPWR_MAX: Maximum permitted MS transmitted power on a specific traffic channel in a specific traffic cell
MS_TXPWR_MAX(n): Maximum permitted MS transmitted power on a specific traffic channel in the n th adjacent traffic cell
NB: Normal burst
NMC: Network management center
NUFR: Receiver noise update flag
NUFT: Noise update flag to ask for SID frame transmission
OMC: Operation and maintenance center
PARCOR: Partial correlation
PCH: Paging channel
PCM: Pulse code modulation
PIN: Personal identity number for MSs
PLMN: Public land mobile network
PLMN_PERMITTED: Boolean flag to indicate whether the MS is permitted to access the specific PLMN
PSTN: Public switched telephone network

QN: Quarter bit number
R: Random number in the authentication process
RA: Rural area channel impulse response
RACH: Random access channel
RF: Radio frequency
RFCH: Radio frequency channel
RFN: Reduced TDMA frame number: equivalent representation of the TDMA frame number that is used in the synchronization channel
RNTABLE: Random number table utilized in the frequency hopping algorithm
RPE: Regular pulse excited
RPE-LTP: Regular pulse excited codec with long term predictor
RS-232: Serial data transmission standard equivalent to CCITT V24. interface
RXLEV: Received signal level: parameter used in handovers
RXQUAL: Received signal quality: parameter used in handovers
S: Signed response in the authentication process
SACCH: Slow associated control channel
SB: Synchronization burst
SCH: Synchronization channel
SCPC: Single channel per carrier
SDCCH: Stand-alone dedicated control channel
SE: Speech extrapolation
SID: Silence identifier
SIM: Subscriber identity module in MSs
SPRX: Speech received flag
SPTX: Speech transmit flag in the DTX handler
STP: Short term predictor
TA: Timing advance
TB: Tailing bits
TCH: Traffic channel
TCH/F: Full-rate traffic channel
TCH/F2.4: Full-rate 2.4-kb/s data traffic channel
TCH/F4.8: Full-rate 4.8-kb/s data traffic channel
TCH/F9.6: Full-rate 9.6-kb/s data traffic channel
TCH/FS: Full-rate speech traffic channel
TCH/H: Half-rate traffic channel
TCH/H2.4: Half-rate 2.4-kb/s data traffic channel
TCH/H4.8: Half-rate 4.8-kb/s data traffic channel
TDMA: Time division multiple access
TMSI: Temporary mobile subscriber identifier
TN: Time slot number
TU: Typical urban channel impulse response

TXFL: Transmit flag in the DTX handler

UL: Up link

VAD: Voice activity detection

VE: Viterbi equalizer

VLR: Visiting location register

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